# **IRB 1600ID**

# **Industrial robot**

MAIN APPLICATION Arc welding



# Dedicated arc welding robot

In IRB 1600ID (Integrated Dressing), all cables and hoses are routed inside the upper arm, making the robot perfectly suitable for arc welding. The dress pack carries all the media necessary for arc welding, including power, welding wire, shielding gas and pressurized air.

# Improving lifetime prediction

Faulty process cabling is a common cause of unpredicted line stops. With the IRB 1600ID, stops can be reduced to a minimum. Because the cables are routed inside the upper arm, their motion is predicted given a certain cycle. And when the motion is predicted, so is the lifetime.

# Increased accessability

Integrated dressing makes the robot's outer dimensions smaller. This extends the robot system's real working range, a crucial factor when welding on fixtures with a complex geometry. It also eliminates the risk of damaging the dress pack in case of collision with the fixture.

# Simplifying robot programming

There is always a blind spot when programming a converntional robot. Because of the external routing and unpredictable motion of the dress pack, programmers have to use their imagination to ensure the dress pack won't hit anything during operation.

# Prolonging cable service life

Having the dress pack routed inside the robot's upper arm gives less swing of the dress pack and the lifetime of all cables and housings is increased.



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# TECHNICAL DATA, IRB 1600ID INDUSTRIAL ROBOT

### SPECIFICATION

| Robot versions<br>IRB 1600ID-4/1.5 | Reach<br>1.5 m      | Handling Capacity<br>4 kg |
|------------------------------------|---------------------|---------------------------|
| Number of axes                     | 6                   |                           |
| Protection                         | IP40                |                           |
| Mounting                           | Floor, and inverted |                           |
|                                    |                     |                           |

#### PERFORMANCE

| Positions repeatability | y 0.02 mm      |          |        |
|-------------------------|----------------|----------|--------|
| Path repeatability      | 0.48 mm        |          |        |
| Axis movements          | Working range  | Axis max | speed  |
| Axis 1 Rotation         | +180° to-180°  | Axis 1   | 180°/s |
| Axis 2 Arm              | +150° to -90°  | Axis 2   | 180°/s |
| Axis 3 Arm              | +79° to -238°  | Axis 3   | 180°/s |
| Axis 4 Wrist            | +155° to -155° | Axis 4   | 320°/s |
| Axis 5 Bend             | +135° to -90°  | Axis 5   | 380°/s |
| Axis 6 Turn             | +200° to -200° | Axis 6   | 460°/s |
|                         |                |          |        |

Axis 4 and 6 together max. +300° to -300°

A supervision function prevents overheating in applications with intensive and frequent movements.

#### ELECTRICAL CONNECTIONS

| JNS  |
|--|
| 200-600V, 50/60 Hz   |
| ISO-Cube at max speed 0.57 kW  |
|  |
| 484 x 648 mm Height: 1392 mm   |
| 250 kg   |
|  |
| chanical unit  |
| +5°C (41°F) to +45°C (113°F)   |
|  |
| -25°C (13°F) to +55°C (131°F)  |
| up to +70°C (158°F)  |
| Max 95%  |
| Max 73 dB (A)  |
| Double circuits with supervisions,<br>emergency stops and safety functions.<br>3-position enable device. |
| EMC/EMI shielded   |
| nged without notice  |
|  |

# WORKING RANGE



