

```
<?xml version="1.0"?>
<launch>

  <remap from="phidgets_getdata_synchronous/IR_1" to="/pedal_monitor/IR_1"/>
  <remap from="phidgets_getdata_synchronous/IR_2" to="/pedal_monitor/IR_2"/>
  <remap from="phidgets_getdata_synchronous/ForceVal" to="/pedal_monitor/ForceVal"/>

  <node pkg="pedal_monitor" name="phidgets_getdata_synchronous" type="phidgets_getdata_synchronous">
    <param name="file_name" value="$(find pedal_monitor)/src/calibration_test.xml"/>
  </node>

  <!-- Launch the odometer node -->
  <remap from="odometer/status" to="/pedal_monitor/odometer"/>

  <node pkg="odometer" name="odometer" type="odometer_node">
    <param name="server_ip" value="10.0.0.31"/>
    <param name="server_port" value="120" type="string"/>
  </node>

  <!-- This is a launch file for recording the topics for my thesis -->

  <node pkg="roscpp" type="record" name="roscpp_record"
  args="record -o /media/Data/Data_Record/newtests/bag1

  /pedal_monitor/ForceVal
  /pedal_monitor/IR_1
  /pedal_monitor/IR_2
  /pedal_monitor/odometer
  "/>

</launch>
```