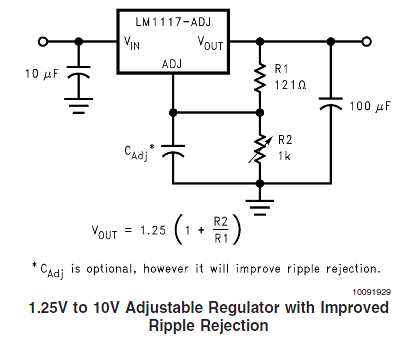
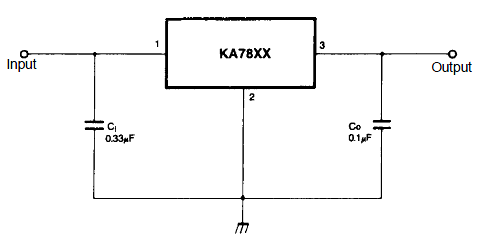
LM117 – 1.25V a 10V para obter os 7.4V para os servos motores



Cin= 10uF Cadj= x Vin\_max= 20V

Cout= 100uF R1= 150 R2= 1k

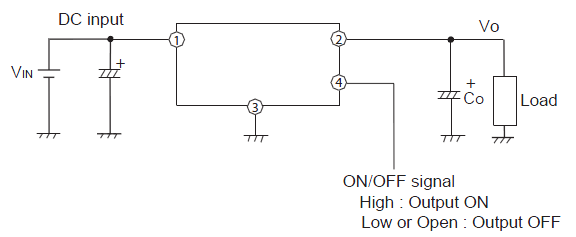
KA7805 – 7.4V para os 5V



Cin= 0.33uF

Cout= 0.1uF Vin\_max= 35V

PQ033EF01SZH – 5V para os 3.3V



Cin= 0.33uF

Cout= 47uF Vin\_max= 10V