Erratum

Title of Subsection 2.1.1 is to change from 'Load cells and calibration' to 'Load cells'.

In Subsection 3.3, Module *haptic_ force*, Figure 3.5 and it's legend are to be changed for the ones below.
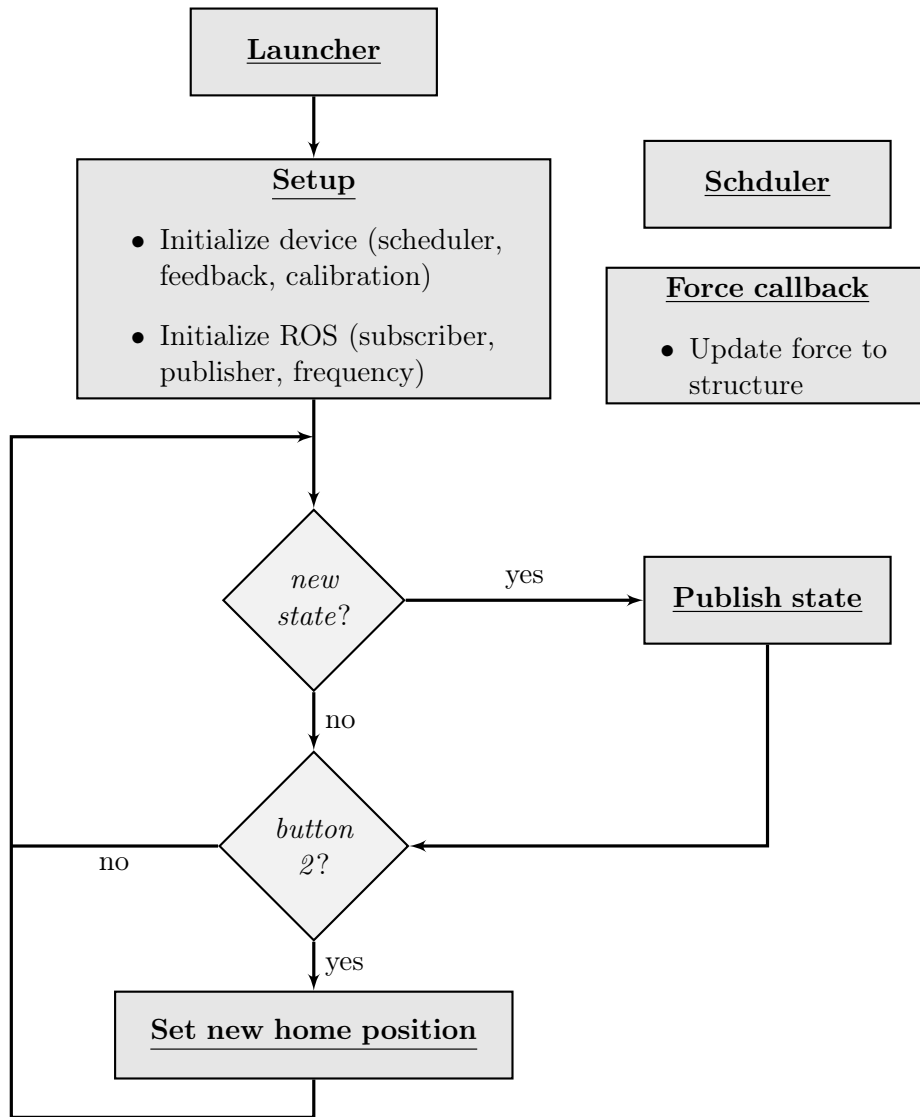

Figure 3.5: Program structure of the *phantom_ control node*.

In Chapter 4, Robot's demonstrations, in the paragraph before Figure 4.2 there is a missing sentence. The following sentence is to be added at the end of the paragraph: *'In all of the demonstrations, the used arrangement of the load cells in the robor's feet is depicted in Figure 4.2.1 where the red cells correspond to the LSB-10 and the blue cells to the LBS-5.'*
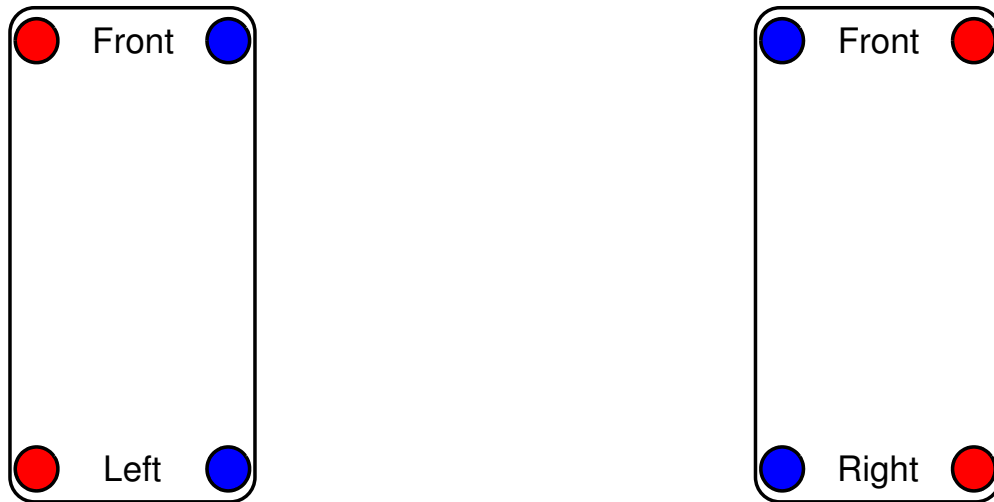
After Figure 4.2, the Figure 4.2.1 is added as follows.

Figure 4.2.1: Load cells arrangement for the demonstrations.