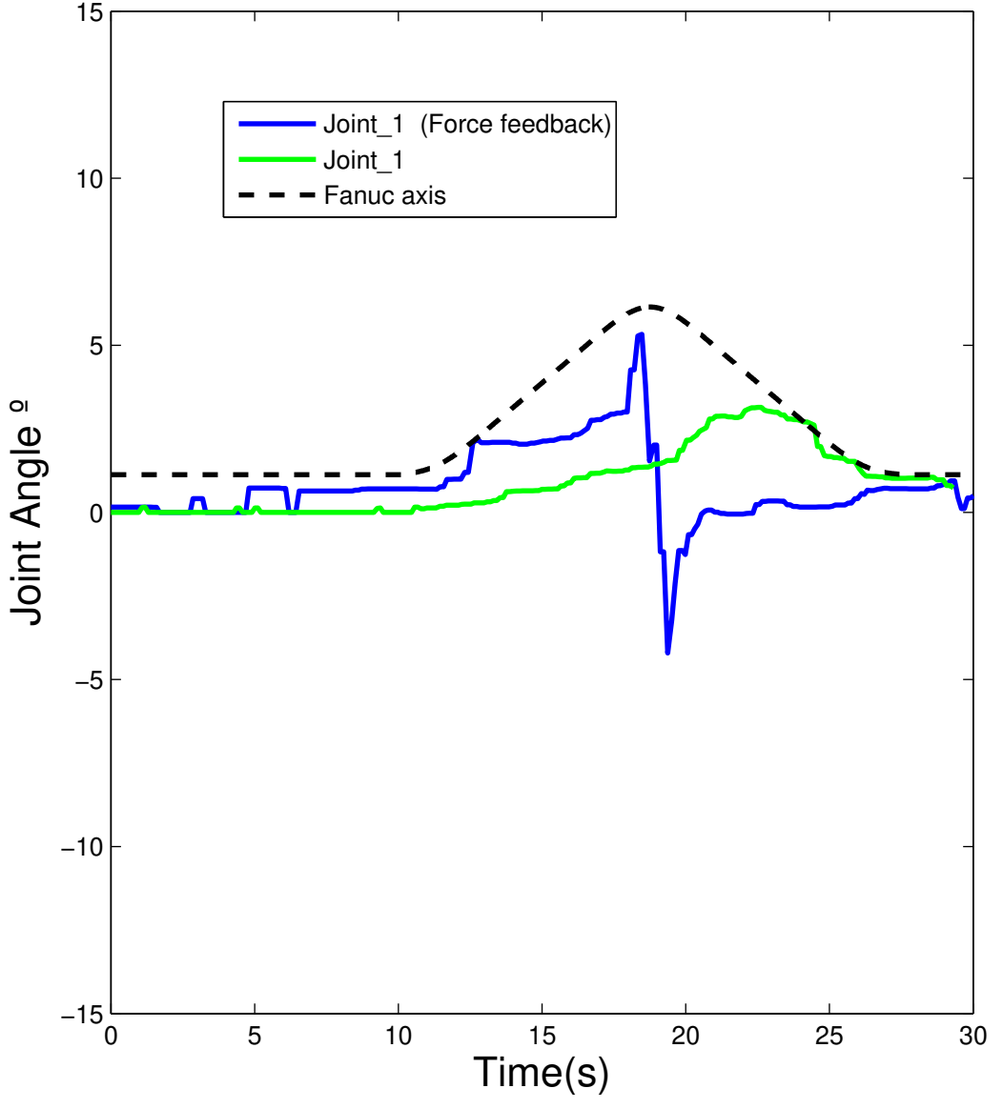
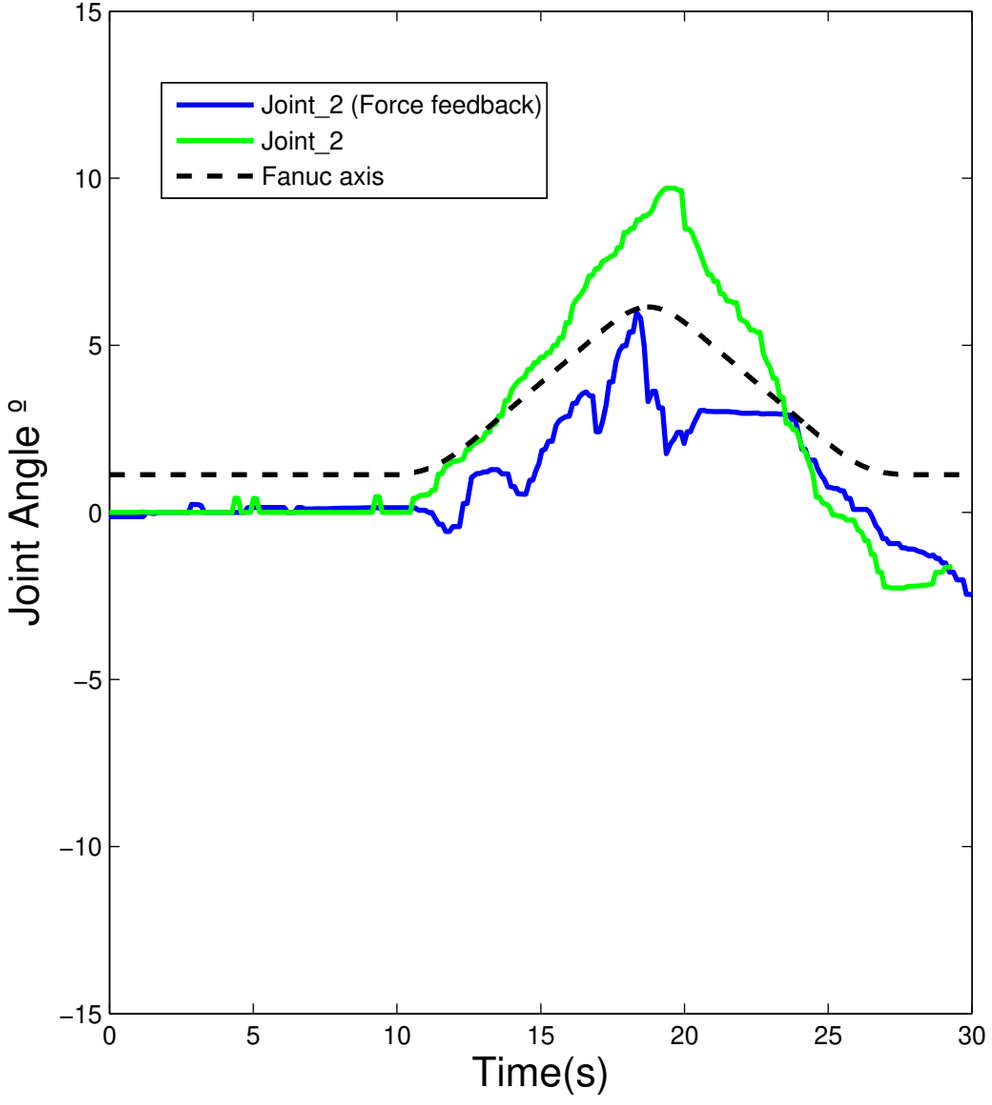

Joint_1 (Force feedback)
Joint_1
Fanuc axis
Joint Angle º
Time(s)
15
10
5
0
−5
−10
−15
0
5
10
15
20
25
30


Joint_2 (Force feedback)
Joint_2
Fanuc axis
Joint Angle º
Time(s)
15
10
5
0
−5
−10
−15
0
5
10
15
20
25
30