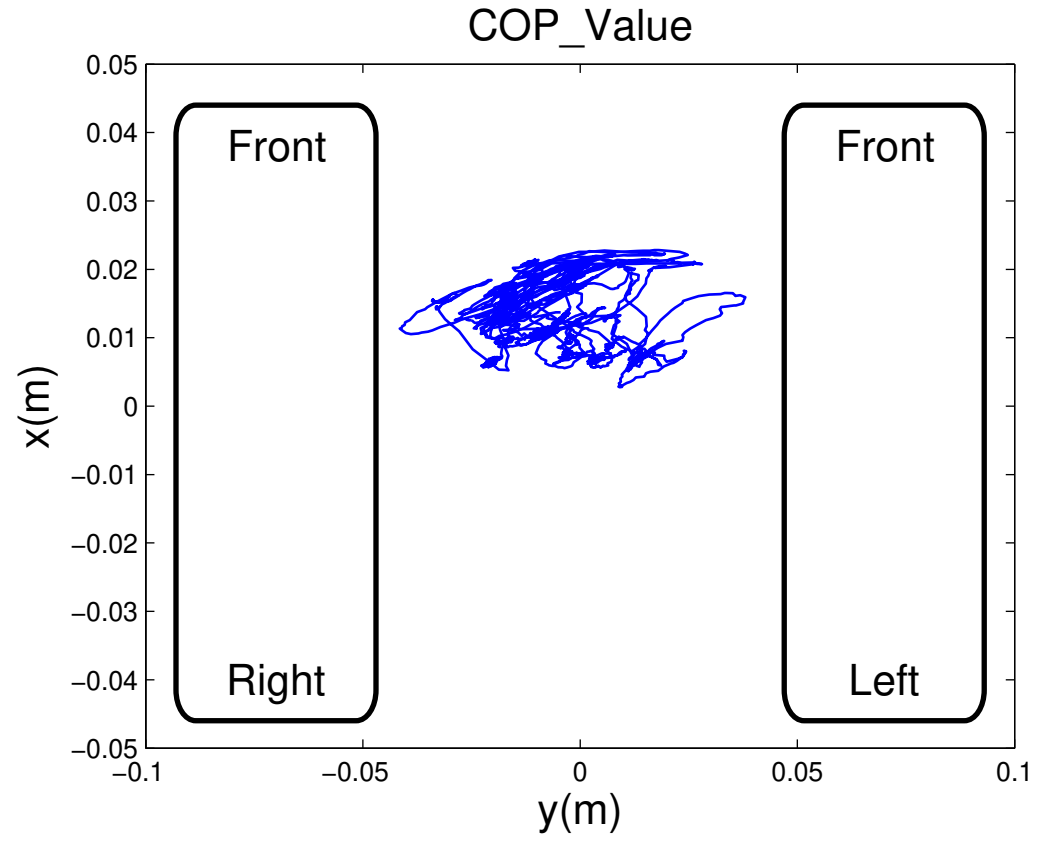
COP_Value
Front
Front
Right
Left
x(m)
y(m)
0.05
0.04
0.03
0.02
0.01
0
−0.01
−0.02
−0.03
−0.04
−0.05
−0.1
−0.05
0
0.05
0.1