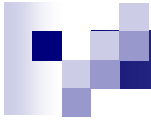


# Redes de Comunicação em Ambientes Industriais Aula 3

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# In the previous episode ...

- Distributed systems **application domains** and **general concepts**
- Requirements
  - Short data, short periods, low jitter, low latency
- Notion of **message** and **transaction**
- Temporal behavior merit figures
  - Network induced delay, delay jitter, buffers requirements, ...
- Data exchange semantics: **event** and **state**
- **Time** and **event triggering**



# Outline

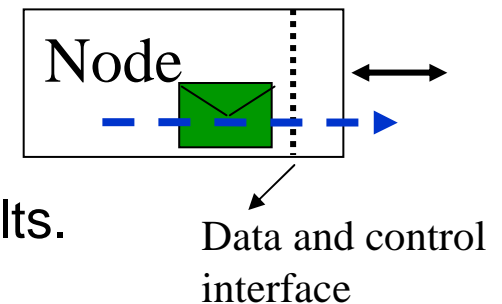
- Transmission control
  - who triggeres message transactions
- Information flow
- Operation flexibility
- Protocol stacks

# Transmission control

- ✓ Determines **who** triggers network transactions, application or network

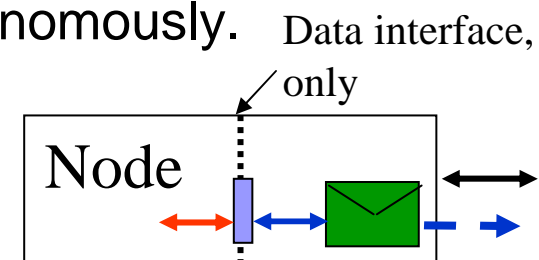
- ✓ **External control**

Transactions are triggered upon explicit control signal from the application. Messages are queued at the interface. Highly sensitive to application design/faults.



- ✓ **Autonomous control**

The network triggers transactions autonomously. No control signal crosses the CNI. Applications exchange data with the network by means of buffers. Deterministic behavior.



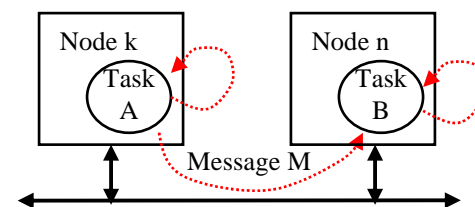
# Transmission control

- ✓ All 4 **combinations** of network type and transmission control are possible, depending on how much global a priori knowledge there is and whether it is located within or outside the network:
  - ✓ **ET network with external control**  
no global a priori knowledge
  - ✓ **TT network with autonomous control**  
network includes global a priori knowledge
  - ✓ **ET network with autonomous control**  
some global a priori knowledge within the network  
(e.g. predefined servers per node)
  - ✓ **TT network with external control**  
global a priori knowledge kept by the application but outside the network

**Typical approaches to combine ET and TT**

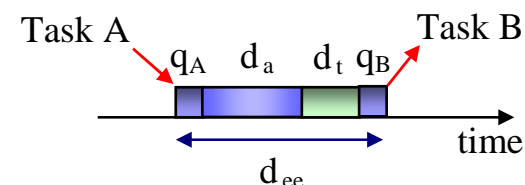
# Information flow

- ✓ Determining **end-to-end delay**



- ✓ **ET-network with external control**

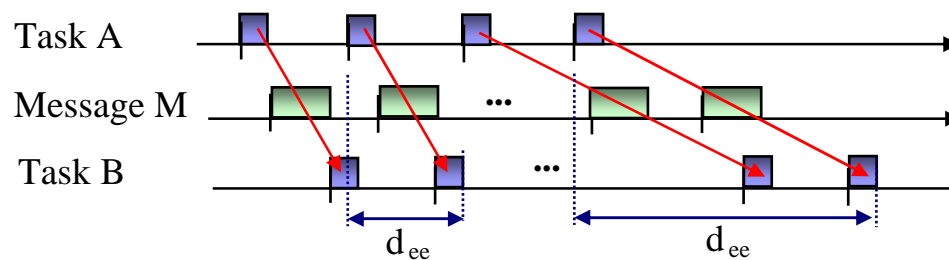
Transactions are composed of several elementary actions carried out in sequence.



- ✓ **TT-network with autonomous control**

The elementary actions in each intervenient (transmitter, network, receiver) are decoupled, spinning at an appropriate rate.

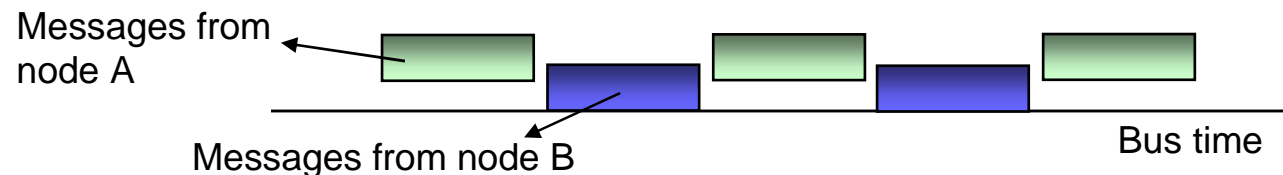
**Requires relative phase control to avoid high delays and jitter**



# Information flow

## ✓ In a TT-network

- ✓ The tight control of the relative phase required between all system activities (message transmissions and task executions) imposes **rigid architectural** constraints
  - ✓ **Time-triggered architecture**
- ✓ The whole system must be designed altogether (network and nodes)
- ✓ However, once the network is designed, nodes will not interfere with each other (transmissions occur in disjoint intervals)
  - ✓ **Composability with respect to temporal behavior**



# Operational Flexibility

- ✓ There is a growing interest in using Distributed Embedded Systems in **dynamic operational scenarios**:
  - ✓ Systems with **variable number of users**, either humans or not (traffic control, radar...)
  - ✓ Systems that operate in **changing physical environments** (robots, cars...)
  - ✓ Systems that can **self-reconfigure dynamically** to cope with hazardous events or evolving functionality (cars, planes, ...)

Buzz words:

***QoS adaptation, graceful degradation, survivability***





# Operational Flexibility

- ✓ Network requirement:  
**Dynamic (flexible) management of bandwidth**  
while guaranteeing real-time constraints
  - ✓ Act upon **periodic communication**, e.g. related to **control information** (potentially bandwidth consuming)
  - ✓ **Adapt transmission rates** according to **effective needs**
  - ✓ Explore subsystems that **operate occasionally**
  - ✓ Explore **variable sampling/tx rates** according to the current system **control stability state**

# Operational Flexibility

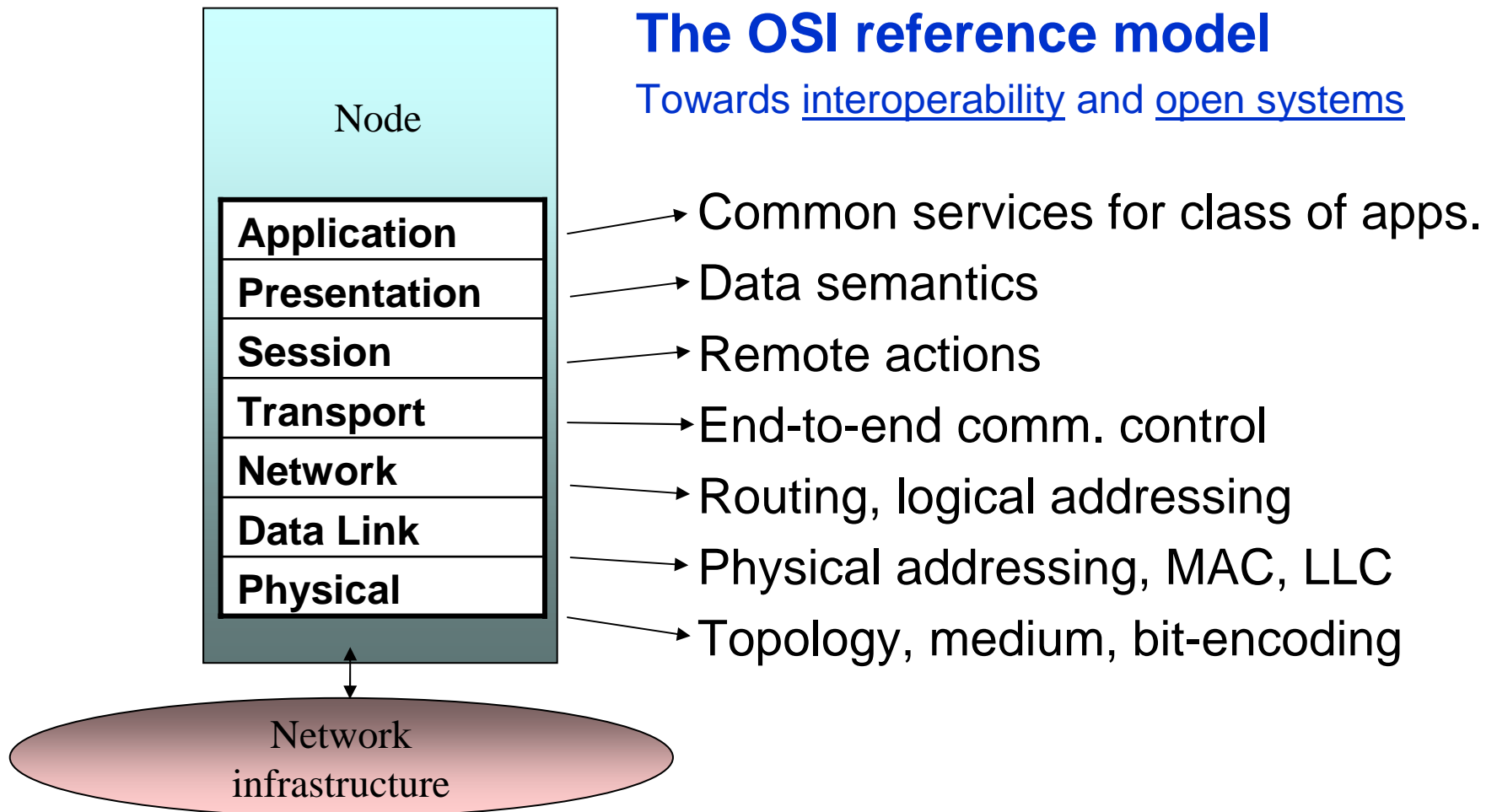
- ✓ **ET-networks are inherently flexible** wrt the communication requirements
- ✓ **TT-networks are not** because of a priori knowledge (normally static)

## Question:

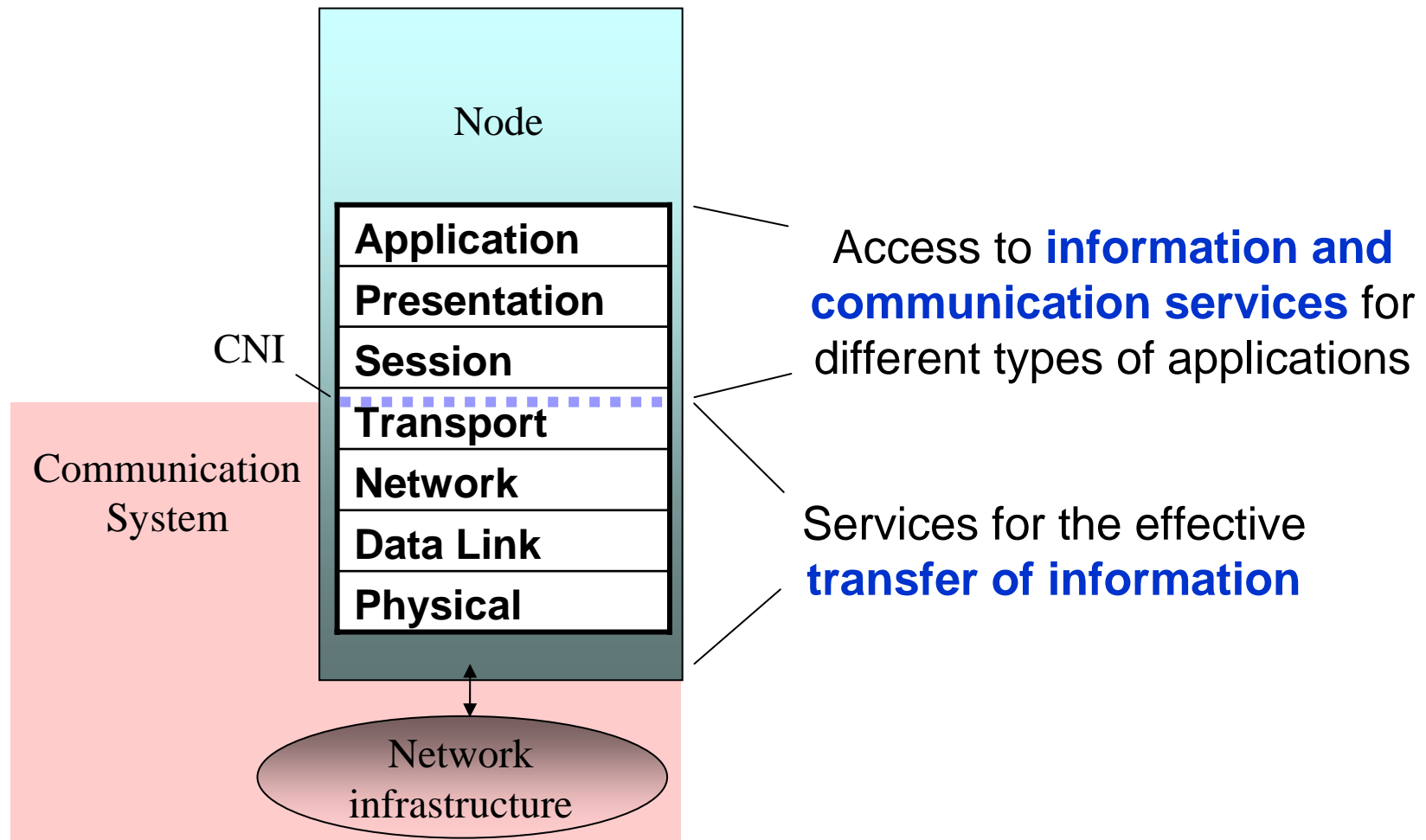
Are the TT-networks excluded when we need operational flexibility?

- ✓ **NO, flexibility of TT-networks** can be improved with:
  - ✓ **Multiple operational modes** that can be switched on-line
  - ✓ **On-line scheduling** of the **periodic traffic**:
    - **FTT paradigm** (Flexible Time-Triggered communication)

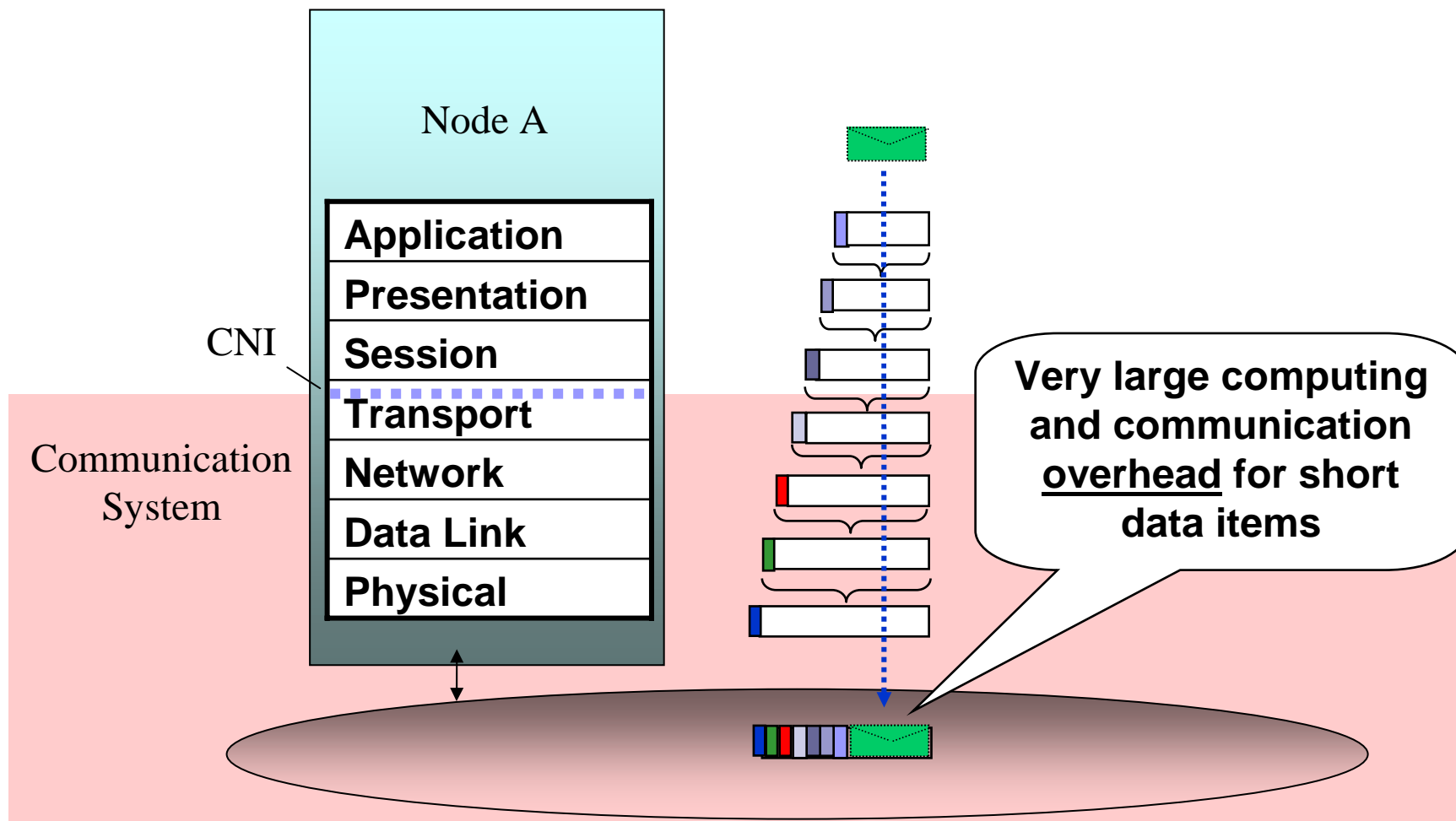
# Protocol stack



# Protocol stack



# Protocol stack

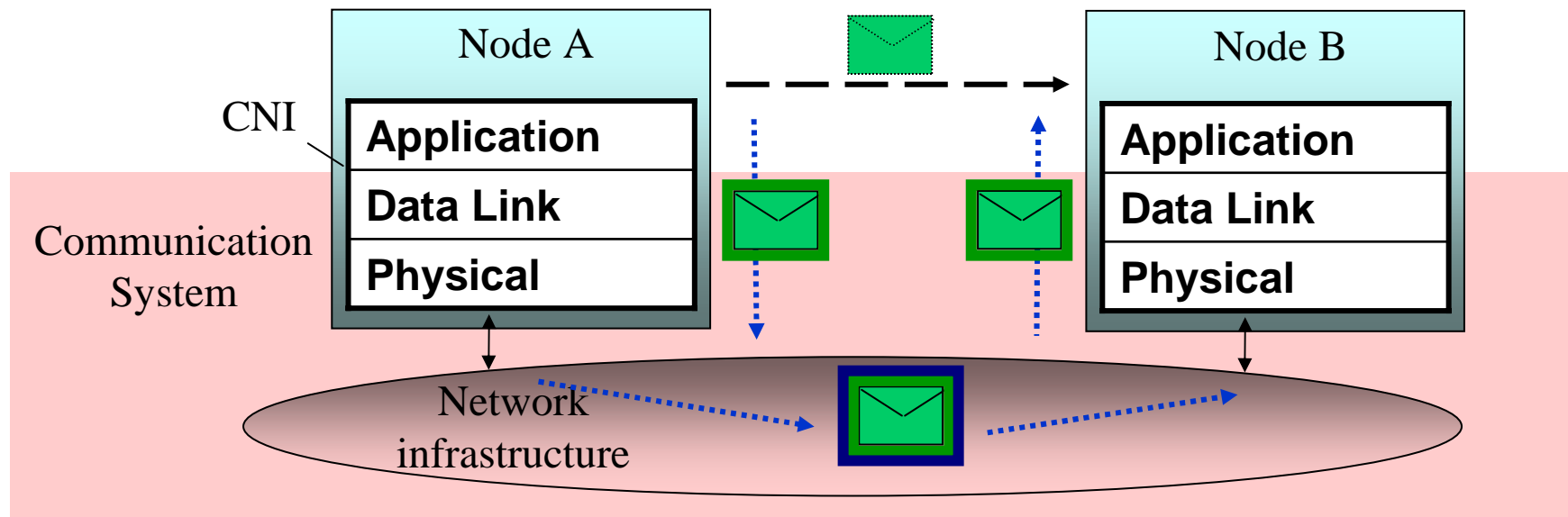


# Real-time protocol stack

- ✓ The **end-to-end communication delay** must be **bounded**
  - ✓ **All services** at all layers must be **time-bounded**
  - ✓ Requires appropriate **time-bounded protocols**
  
- ✓ The **7 layers** impose a considerable computation and communication **overhead**...
  - ✓ The time to execute the protocol stack becomes dominant wrt the communication time
  
- ✓ Many real-time networks
  - ✓ are dedicated to a well defined application (no need for presentation)
  - ✓ use single broadcast domain (no need for routing)
  - ✓ use short messages (no need to fragment/reassemble)

# OSI collapsed model

- ✓ **Application** services access the **Data Link** directly
- ✓ Other layers maybe present but not fully stacked
- ✓ In process control and factory automation these networks are called **Fieldbuses**



# Summary:

- ✓ Transmission **control** can be **external** or **autonomous**
- ✓ **TT networks** with **autonomous control** require **judicious use of relative phase** to avoid high delays and jitter → Time-triggered architecture
- ✓ **ET networks** are inherently **flexible** at run-time
- ✓ **TT networks** are typically **static** but can use multiple modes or on-line scheduling of the periodic traffic



## Summary (cont.)

- ✓ The **OSI 7 layers** reference model imposes **too much overhead** for real-time networks (mainly in embedded control applications)
- ✓ **Real-time** properties must be enforced in **all layers**
- ✓ Real-time networks frequently use a **collapsed 3 layers** structure:
  - ✓ **physical**, **data link** and **application** layers