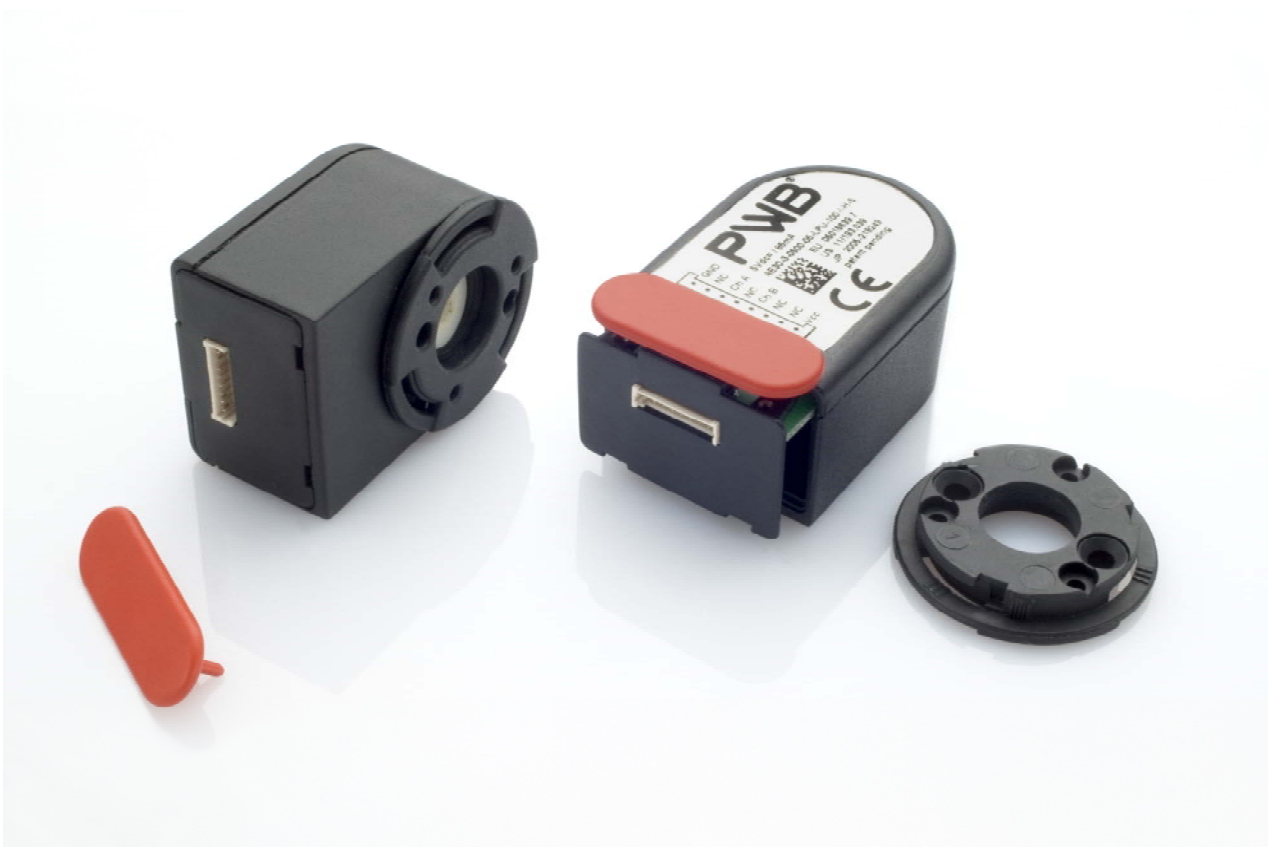


Data Sheet AE30 2/3-Channels pull-up version



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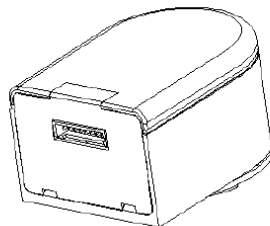
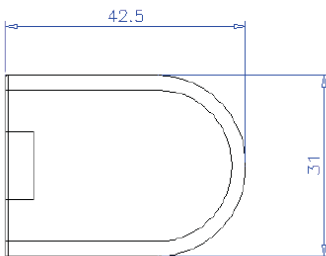
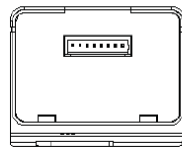
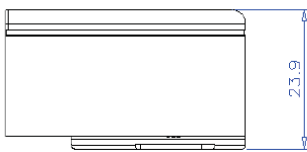
Description

The AE30 is a reliable low cost optical hollow shaft encoder that can be fixed quickly and easily on different sizes of motor shafts.

The encoder provides two square wave outputs in quadrature (90 degrees phase shifted) and one optional index channel (one pulse per rotation).

The resolution of the encoder is determined by the number of Counts Per Rotation (CPR). Power supply and signals are provided by an 8 pin Molex connector or with Flat cable with AMP connector.

Dimensions



Encoder Counts Per Rotation (CPR)
100
200
256
360
400
500
512
1000
1024

Main characteristics

- Hollow shaft encoder
- High performance in compact size
- Robust plastic housing
- Quick and easy assembly
- Resolutions up to 1024 counts per revolution (CPR)
- Up to 100 kHz output frequency
- Two channel quadrature output (A / B)
- Two channel quadrature output with index pulse (A / B / I)
- TTL compatible outputs
- Output circuit : pull-up
- Operating temperature range -40 °C to +100 °C
- Several shaft diameter options
- No signal adjustment required
- Compliant EU-directive 2002/95/EG (RoHS)

Motor shaft Ø Diameter (mm)
A = 1.800
B = 2.000
C = 2.500
D = 3.000
E = 3.175 (1/8")
F = 3.969 (5/32")
G = 4.000
H = 4.763 (3/16")
I = 5.000
J = 6.000
K = 6.350 (1/4")
L = 8.000

Applications

- For high volume applications like factory and office automation
- Consumer electronics, white goods, automatic handlers, doors and windows controls

Absolute Maximum Ratings

Parameter	Symbol	Min.	Typ.	Max.	Unit	Notes
Storage Temperature	T _S	-40		100	°C	
Supply Voltage	V _{CC}	-0.5		to 7.0	V _{DC}	
Output Voltage	V _{out}	-0.5		to V _{CC}	V	
Output Current	I _{out}	-1.0		5.0	mA	per Channel

Recommended Operating Conditions

Encoding Characteristics over Recommended Operating Range and Recommended Mounting Tolerances unless otherwise specified.

Parameter	Symbol	Min.	Typ.	Max.	Unit	Notes
Operating Temperature ^{M1}	T _A	-40		100	°C	
Operating Temperature ^{M2}	T _A	-40		85	°C	
Supply Voltage	V _{CC}	4.5	5.0	5.5	V _{DC}	Ripple < 100 mV _{p-p}
Load Capacitance	C _L			100	pF	pull-up 3.3 kΩ
Count Frequency	f			100	kHz	rpm x CPR / 60

Note:

M1/M2: see ordering codes

The Encoder performance is guaranteed up to 100 kHz, higher frequencies are allowed (for details please contact our customer support)

Electrical characteristics

Parameter	Symbol	Min.	Typ.	Max.	Unit	Notes
Supply current	I _{CC}			85	mA	
High level output voltage	V _{OH}	2.4			V	I _{OH} = -200 μA
Low level output voltage	V _{OL}			0.4	V	I _{OL} = 3.86 mA
Output waveform rise time	t _r		200		ns	C _L = 25 pF R _L = 1 MΩ V _{CC} = 5V T = 25°C
Output waveform fall time	t _f		50		ns	
Ch. I rise after Ch. A or Ch. B fall	t ₁	10	100	250	ns	
Ch. I fall after Ch. A or Ch. B rise	t ₂	70	150	300	ns	

Note: Ch. A & Ch B. quadrature output + Ch. I Index output

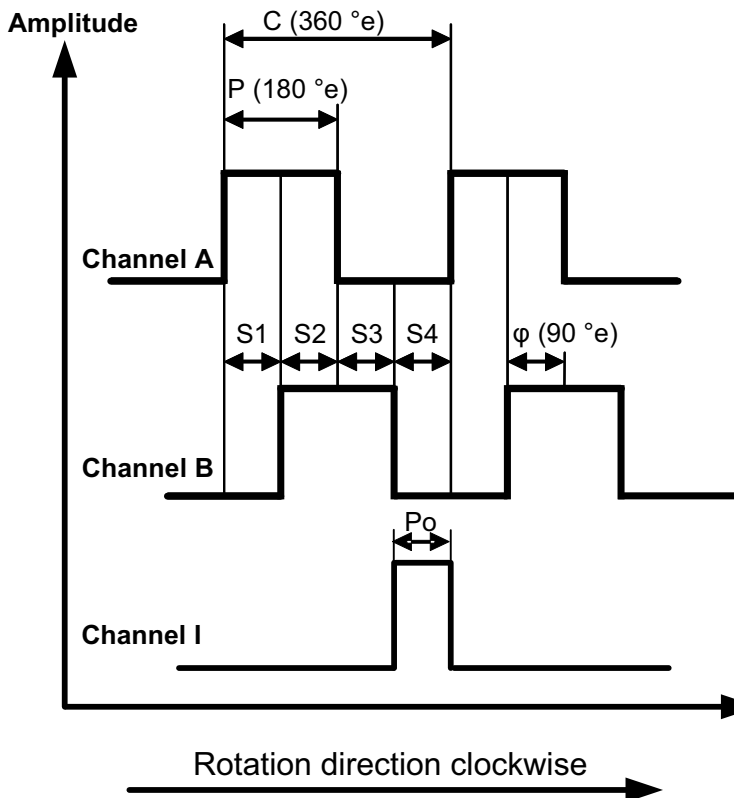
ESD Warning: Normal handling precautions should be taken to avoid static discharge damage to the sensor.

Encoder characteristic

Encoding Characteristics over Recommended Operating Range and Recommended Mounting Tolerances unless otherwise specified.

	Parameter	Symbol	Min.	Typ.	Max.	Unit
2 channel + Index ^{M1}	Pulse width error	ΔP		± 7	± 30	$^{\circ}e$
	State width error	ΔS		± 5	± 30	$^{\circ}e$
	Phase error	$\Delta \Phi$		± 2	± 15	$^{\circ}e$
	Index pulse width	P_0	60	90	120	$^{\circ}e$
2 channel ^{M2}	Pulse width error	ΔP		± 7	± 45	$^{\circ}e$
	State width error	ΔS		± 5	± 45	$^{\circ}e$
	Phase error	$\Delta \Phi$		± 2	± 20	$^{\circ}e$

Note: M1/M2: see ordering codes



Definitions

Count (N): the number of bar and window pairs or increments per revolution (CPR) of the code wheel.

One Cycle C: one period of the signal, related to 1 bar and 1 window. It is measured in electrical degrees, one cycle is 360 electrical degrees ($^{\circ}e$).

Cycle Error (ΔC): the deviation in electrical degrees of the pulse width from its ideal value. It is an indication of cycle uniformity.

Pulse Width (P): the number of electrical degrees when an output is "HIGH" during one cycle, nominally 180 $^{\circ}e$ or half a cycle.

Pulse Width Error (ΔP): the deviation in electrical degrees of the pulse width from its ideal value of 180 $^{\circ}e$.

State Width (S): The number of electrical degrees between a transition in the output of channel A and the neighbouring transition in the output of channel B. There are 4 states per cycle, each nominally 90 $^{\circ}e$ (S1 – S4).

State Width Error (ΔS): The deviation in electrical degrees of each state width from its ideal value of 90 $^{\circ}e$.

Phase (ϕ): The number of electrical degrees between the centre of the high state on channel A and the centre of the high state on channel B. This value is nominally 90 $^{\circ}e$ (the signals A and B can be used for quadrature).

Phase Error ($\Delta \phi$): the deviation in electrical degrees of the phase from its ideal value of 90 $^{\circ}e$.

Index pulse width (P_0): the number of electrical degrees when the index is high during one full shaft rotation.

Connector output

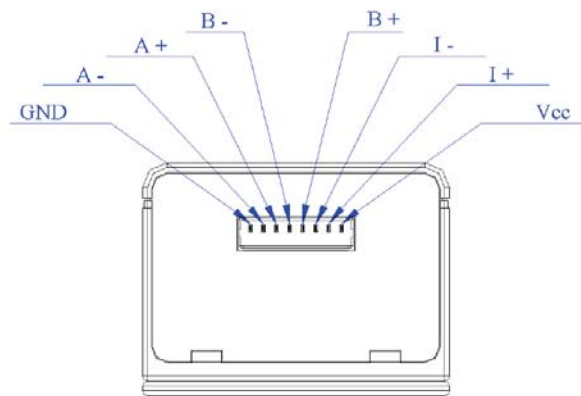
Encoder Header connector: Wennmacher CX-W125R-8-DIP^{M1}
Molex 53048-0810^{M2}

Housing connector: Wennmacher CX-H-125-8 with CX-T125F Terminals^{M1}
Molex 51021-0800 with 50079-8000 Terminals^{M2}

Note: M1/M2: see ordering codes

Pin-out description

Output pin	Description
GND	Ground
A-	(not connected)
A+	Channel A+
B-	(not connected)
B+	Channel B+
I-	(not connected)
I+	Index I+
V_{cc}	Power supply



Mechanical characteristics and drawings

Parameter		Value	Tolerance	Unit
Dimensions		42.5 x 31.0 x 23.9 mm (refer to Page 2)		mm
Weight		17		g
Shaft diameters	Ø	1.8 / 2.0 / 2.3 / 2.5 / 3.0 / 3.175 / 3.969 / 4.0 / 4.763 / 5.0 / 6.0 / 6.35 / 8.0 (see Fig.2 below)	± 0.01	mm
Motor shaft length protrusion	L	9.5 (see Fig.2 below)	+ 1.5	mm
Max. motor mounting boss diameter	D	13.0 (see Fig.2 below)		mm
Max. motor mounting boss height	H	2.0 (see Fig.2 below)		mm
Max. motor axial shaft play			± 0.25	mm
Max. motor shaft eccentricity + radial play		0.05 (eccentricity decreases signal performances)		mm
Screws for fixing		2 X M3 (Din 965) 3X M2 (Din 7985)		
Tightening torque of the screws		15	-5	Ncm
Flange print		Refer to Fig.3 below		
Protection grade		IP50 (according to DIN 40500)*		
Plastic material		PBT, 17% glass fibre reinforced UL 94 V-0		

Note: * When the encoder is properly assembled

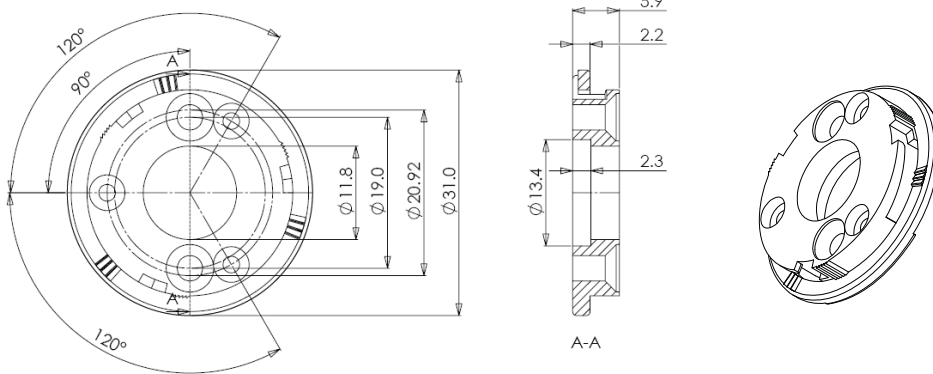


Fig. 1 Flange dimension

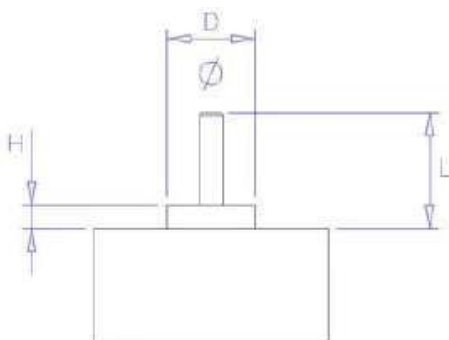


Fig. 2 Motor shaft tip

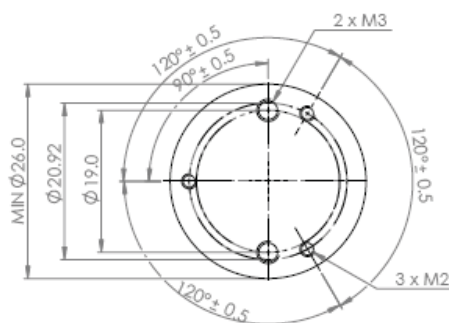
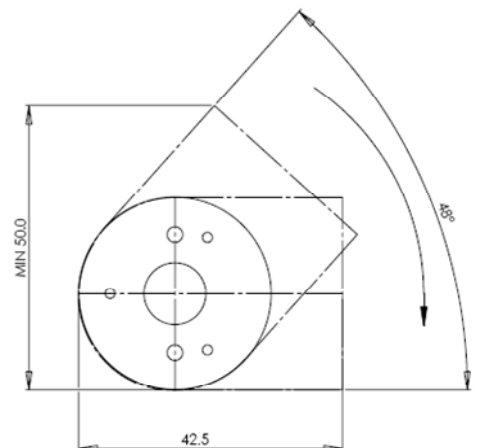


Fig. 3 Flange print



Assembly instruction

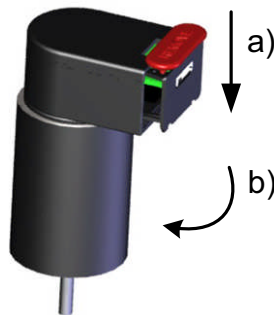
Step 1



The flange is placed onto the motor and fixed by the screws. A centering gauge is available for the correct assembling of the flange.

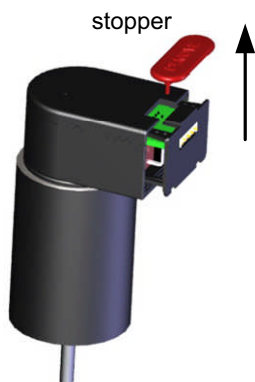
Note: proper centering of the flange is important for the optimal performance of the encoder.

Step 2



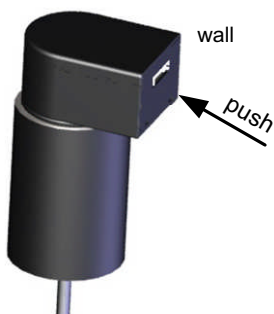
Align the hole of the hub on the motor shaft (a). When the encoder fits totally onto the flange, start to rotate clockwise until a stop point is reached (b).

Step 3



After assembling the encoder on the flange, remove the stopper.

Step 4



Push the wall into the housing into its final position. Now the encoder is ready for use.

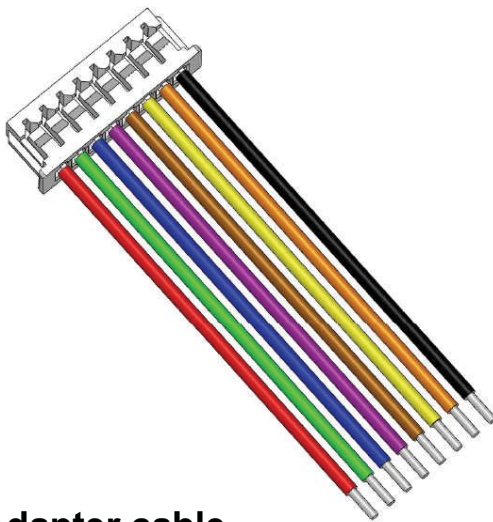
ATTENTION!

The encoder is so designed that it may be assembled only one time, otherwise the guarantee will be voided.

Note: see IMPORTANT NOTICE (page 11)

Available accessories

Standard cable

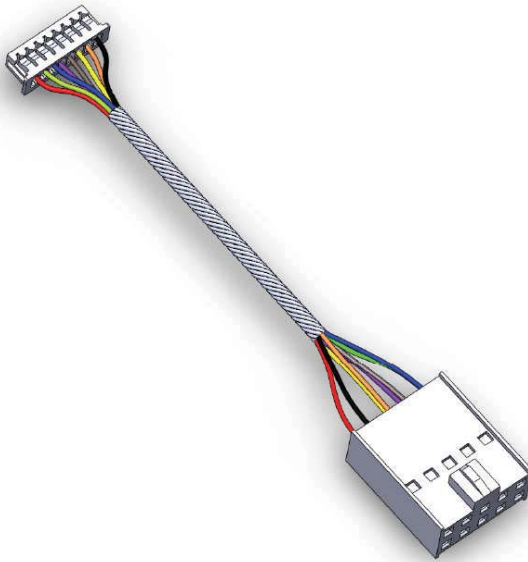


Cable 300 mm length UL1569 / AWG30 ^{M1}
with female Housing connector:
Wennmacher CX-H-125-8 with CX-T125F Terminals

Cable 300 mm length UL1061 / AWG26 ^{M2}
with female Housing connector:
Molex 51021-0800 with 50079-8000 Terminals

Note: M1/M2: see ordering codes

Adapter cable



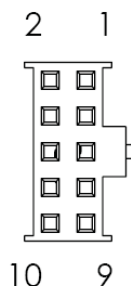
Twisted adapter cable 500 mm length UL1569 / AWG30 ^{M1}
with female Housing connector:
8-pin Wennmacher connector
(Wennmacher CX-H-125-8 Housing with CX-T125F Terminals)
to a 10-pin Molex connector
(Molex 90142-0010 Housing with 90119-2121 Terminals)

Twisted adapter cable 500 mm length UL1061 / AWG26 ^{M2}
with female Housing connector:
8-pin Molex connector
(Molex 51021-0800 with 50079-8000 Terminals)
to a 10-pin Molex connector
(Molex 90142-0010 Housing with 90119-2121 Terminals)

Note: M1/M2: see ordering codes

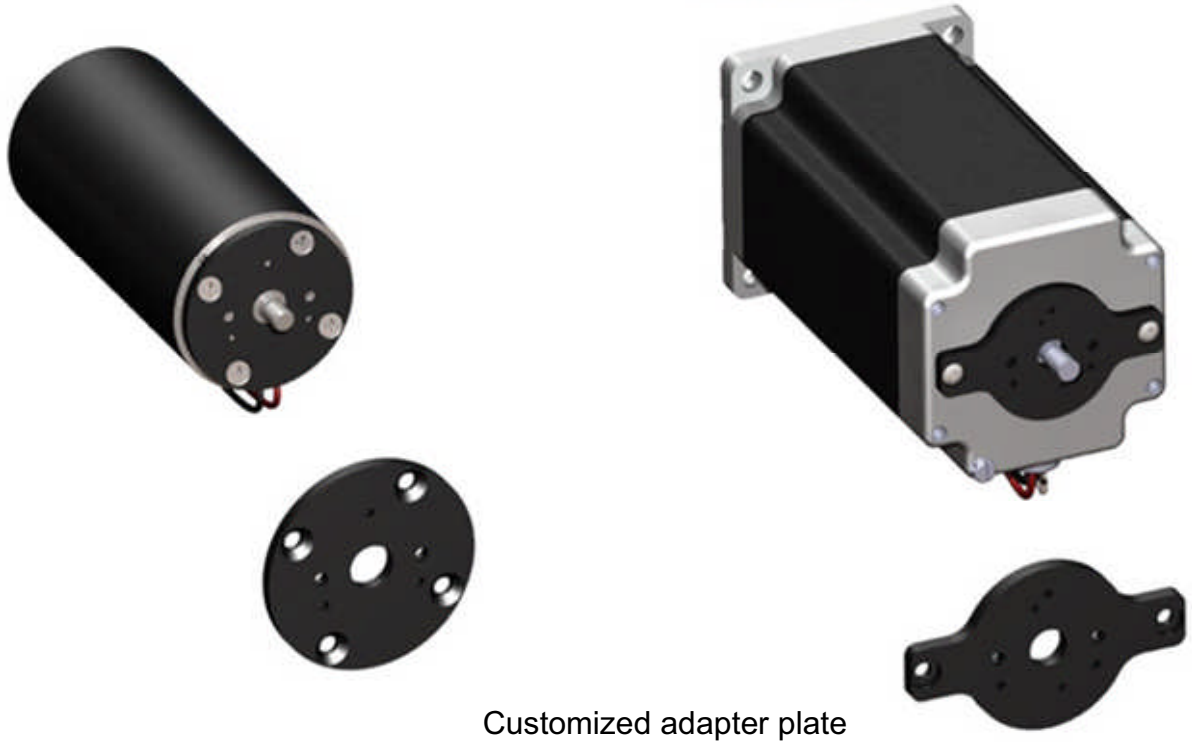
Pin-out description 10 pin connector side

Pin	Output pin	Description	Colors
1	N.C.	Not connected	
2	Vcc	Power supply	red
3	GND	Ground	black
4	N.C.	Not connected	
5	A -	Channel A-	orange
6	A +	Channel A+	yellow
7	B -	Channel B-	brown
8	B +	Channel B+	purple
9	I -	Index I-	blue
10	I +	Index I+	green



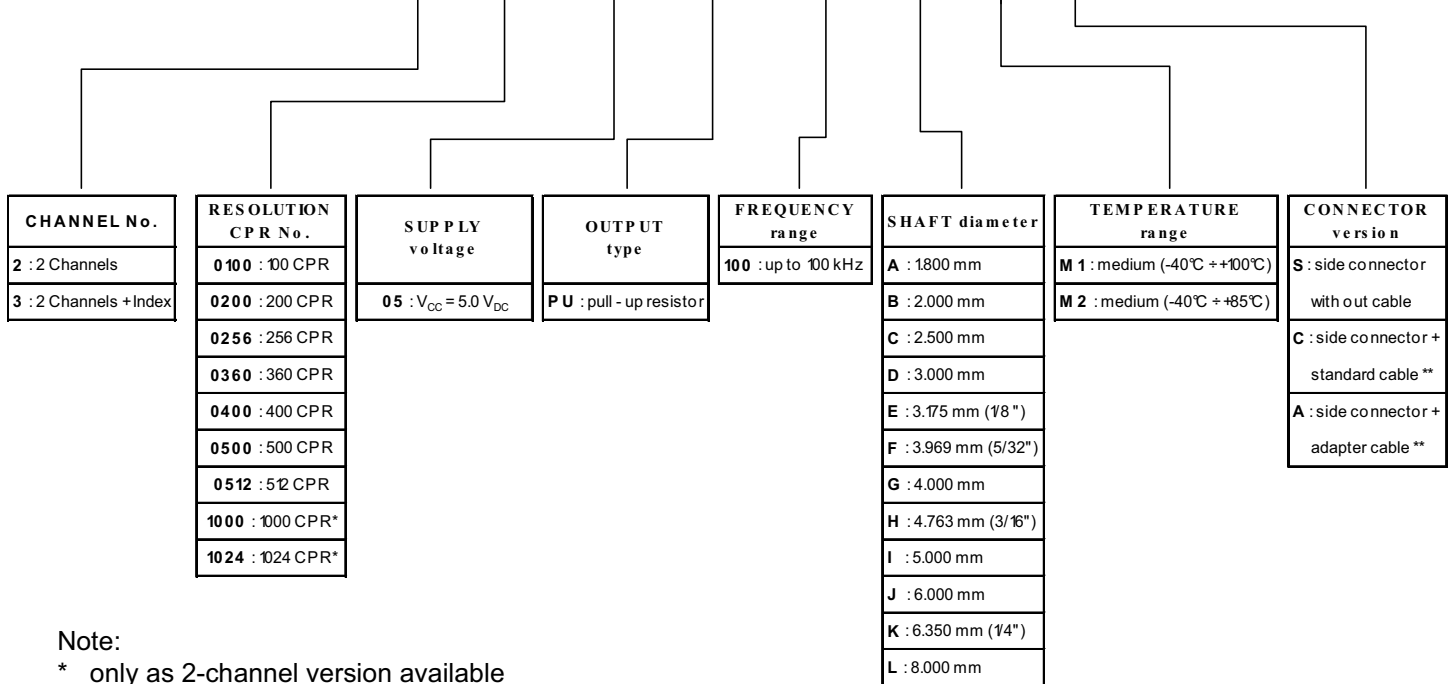
Connector front view

Available accessories



Ordering codes

AE30 - X-XXXX -XX - XX - XXX - X - XX -X



Note:

* only as 2-channel version available

** see page 8

Available accessories (no parts of standard delivery):

- standard cable 300 mm length
- adapter cable 500 mm length
- adapter plates for different motors
- centering gauge for different motor shafts
- fastening screws 3pcs Din 7985 M2 X 8
- fastening screws 2pcs Din 965 M3 X 8

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The guarantee will be voided by misuse, accident, modification, unsuitable physical or operating environment, operation in other than the specified operating environment, or failure caused by a product for which ***PWB-Ruhltec Industrieprodukte GmbH*** is not responsible.

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