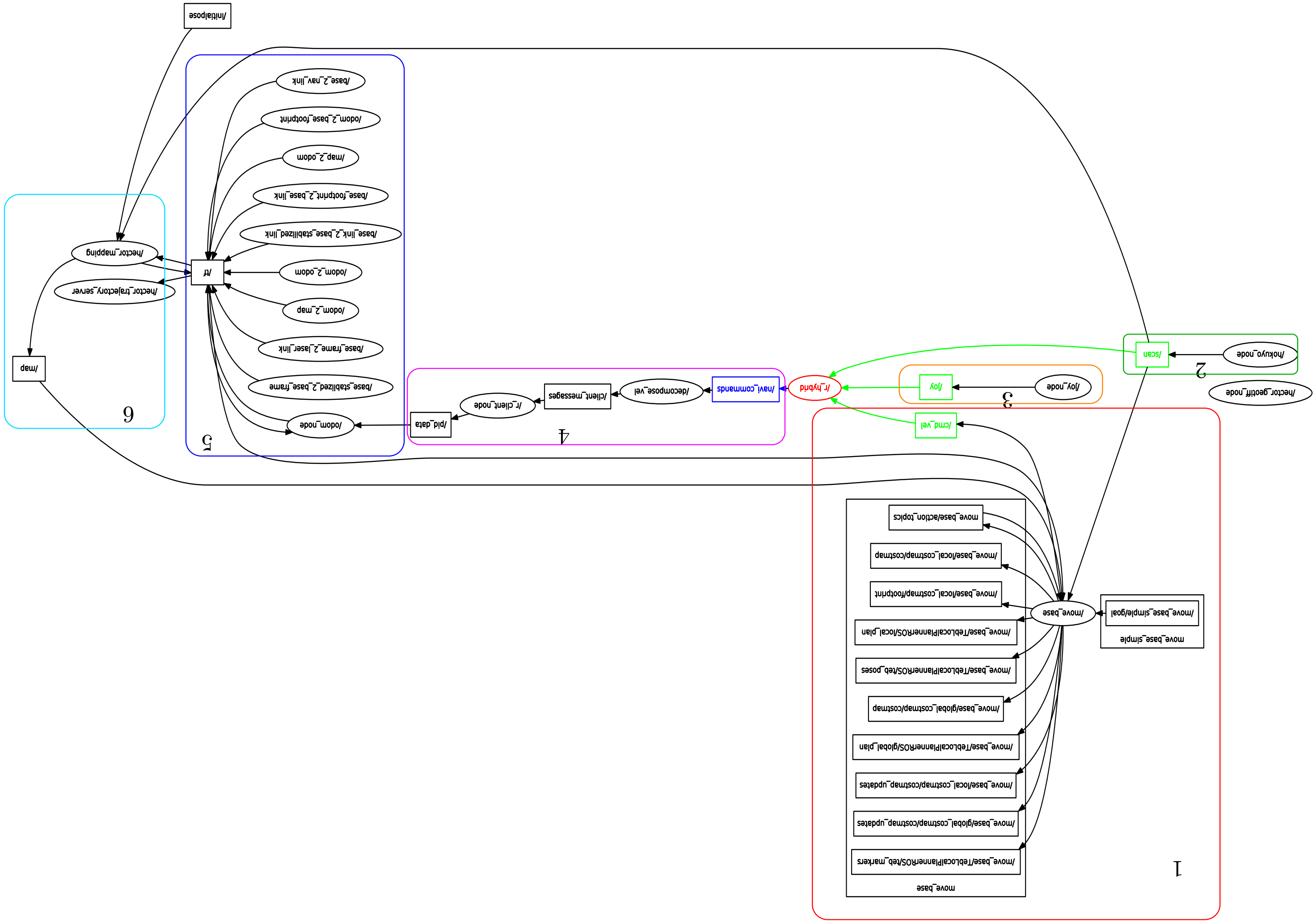
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move_base
/move_base/TebLocalPlannerROS/teb_markers
/move_base/global_costmap/costmap_updates
/move_base/local_costmap/costmap_updates
/move_base/TebLocalPlannerROS/global_plan
/move_base/global_costmap/costmap
/move_base/TebLocalPlannerROS/teb_poses
/move_base/TebLocalPlannerROS/local_plan
/move_base/local_costmap/footprint
/move_base/local_costmap/costmap
move_base/action_topics
move_base_simple
/move_base_simple/goal
/move_base
/cmd_vel
3
/joy_node
/joy
/r_hybrid
/hector_geotiff_node
2
/hokuyo_node
/scan
/navl_commands
/decompose_vel
/client_messages
4
/r_client_node
/pld_data
/odom_node
5
/base_stabilized_2_base_frame
/base_frame_2_laser_link
/odom_2_map
/odom_2_odom
/tf
/base_link_2_base_stabilized_link
/base_footprint_2_base_link
/map_2_odom
/odom_2_base_footprint
/base_2_nav_link
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/map
/hector_trajectory_server
/hector_mapping
/initialpose