

4-Q-EC Servoamplifier DES 70/10

DIGITAL CAN RS232 GUI



- Power**
 - Power supply
 - Motor windings
- Signal**
 - Terminal for inputs
 - Terminal for outputs
- Encoder**
 - Connector for Digital-Encoder
- DIP switch**
 - Adjustment CAN-ID, Set value
- Potentiometer**
 - Parameter adjustments
- LED**
 - Status indicator

Advantages

- 4-Q operation
- Excellent price / performance ratio
- Operating modes
- Digital
- Easy start-up procedure
- Protection circuit
- PC based commanding

Features

Controlled operation for acceleration and braking in both directions

Modern digital servoamplifier with sinusoidal commutation (minimal torque ripple, low noise) for perfect speed controlled operation of brushless EC motors with Hall sensors and Digital Encoder with LineDriver

Digital speed control, digital current control

New generation of Digital Signal Processors (DSP) allows fast digital controlling. Achievable numerical specification of constant and reproducible parameters

Easy connection, suitable for maxon EC motors

Easy trimming with just a few potentiometers or, as an alternative configuration and commanding by serial interface (RS232 or CAN)

Protected against excess current / short circuit on the motor winding and excess voltage

Supported by Graphical User Interface (GUI), Windows DLL for RS232 with several sample programs.

Electrical Data

- Supply voltage V_{CC} (Ripple < 5 %) 24 - 70 VDC
- Max. output voltage $0.9 \times V_{CC}$
- Max. output current I_{max} 30 A
- Continuous output current I_{cont} 10 A
- Switching frequency of power stage 50 kHz
- Max. efficiency 92 %
- Band width current controller 1 kHz
- Max. speed (motor with 2 poles) 25 000 rpm
- Built-in motor choke per phase none
- (min. necessary link inductances 400 μ H)

Inputs

- Set value configurable
- Enable -10 ... +10 V ($R_i = 80 \text{ k}\Omega$), 0 ... +5 V ($R_i = 50 \text{ k}\Omega$)
- Digital 1 (Switch «Monitor n» / «Monitor l») +2.4 ... +50 VDC ($R_i = 12 \text{ k}\Omega$)
- Digital 2 (Switch speed / current controller) +2.4 ... +50 VDC ($R_i = 17 \text{ k}\Omega$)
- STOP +2.4 ... +50 VDC ($R_i = 90 \text{ k}\Omega$)
- Encoder signals A, A', B, B', I, I' max. 1 MHz
- 3-channels encoder is required
- Hall sensor signals H1, H2, H3

Outputs

- Monitor can be configured with DIP switch 9:
 - 10 ... +10 VDC ($R_0 = 1 \text{ k}\Omega$, $f_g = 900 \text{ Hz}$)
 - 0 ... 5 VDC ($R_0 = 1 \text{ k}\Omega$, $f_g = 900 \text{ Hz}$)
- Status reading «READY» ;
 - Open Collector max. 30 VDC ($I_L < 20 \text{ mA}$)

Voltage outputs

- Encoder supply voltage +5 VDC, max. 100 mA
- Hall sensor supply voltage +5 VDC, max. 50 mA
- Auxiliary supply voltage +5 VDC, max. 20 mA

Interface

- RS232 RXD; TXD (max. 115 200 Bit / s)
- CAN high; low (max. 1 Mbit / s)

Trim potentiometers

- n_{max} • Offset • I_{max} • gain

LED indicator

- Bi-colour LED READY / ERROR
- green = READY, red = ERROR

Ambient temperature / humidity range

- Operation -10 ... +45°C
- Storage -40 ... +85°C
- No condensation 20 ... 80 %

Mechanical data

- Weight approx. 400 g
- Mounting plate Flange for M4-screws

Connection

- **Power / Signal**
 - Power 6 pole / Signal 20 pole (2 x 10)
 - Pitch Power 5.08 mm / Signal 2.54 mm
 - Wire cross section: AWG 26 - 16
 - Power 0.14 - 1.5 mm² multiple-stranded wire
 - 0.14 - 1.5 mm² single wire
 - Signal 0.14 - 0.5 mm² multiple-stranded wire
 - 0.14 - 0.5 mm² single wire

Encoder

- Plug DIN41651 (10 pole)
- for flat band cable, pitch 1.27 mm with AWG28

Order number

- DES 70/10** digital 4-Q-EC Servoamplifier
- 228597** in module housing

Accessories

- 232359** Choke module 3 x 0.15 mH each 10 A
- 223774** Encoder adapter according to DIN41651 on screw terminal
- 235811** Shunt regulator

Dimensions in [mm]

