

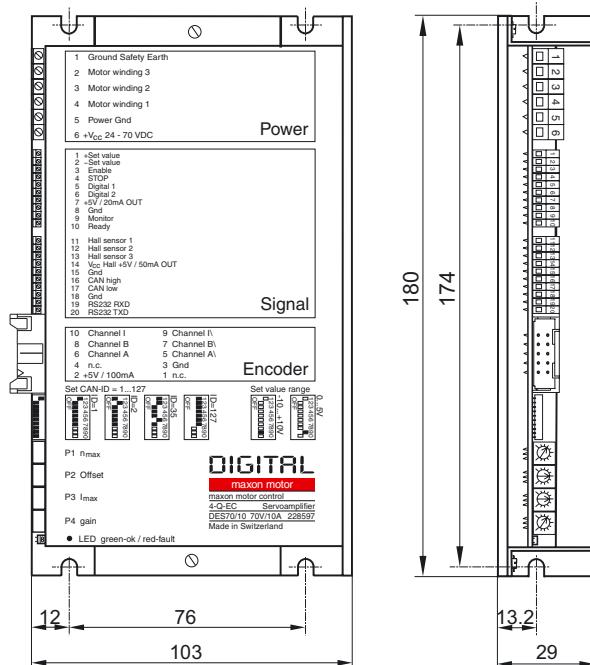
## Advantages

- 4-Q operation
- Excellent price / performance ratio
- Operating modes
- Digital
- Easy start-up procedure
- Protection circuit
- PC based commanding

## Features

- Controlled operation for acceleration and braking in both directions
- Modern digital servoamplifier with sinusoidal commutation (minimal torque ripple, low noise) for perfect speed controlled operation of brushless EC motors with Hall sensors and Digital Encoder with LineDriver
- Digital speed control, digital current control
- New generation of Digital Signal Processors (DSP) allows fast digital controlling. Achievable numerical specification of constant and reproducible parameters
- Easy connection, suitable for maxon EC motors  
Easy trimming with just a few potentiometers or, as an alternative configuration and commanding by serial interface (RS232 or CAN)
- Protected against excess current / short circuit on the motor winding and excess voltage
- Supported by Graphical User Interface (GUI), Windows DLL for RS232 with several sample programs.

Dimensions in [mm]



## Electrical Data

• Supply voltage V <sub>CC</sub>	24 - 70 VDC
(Ripple < 5 %)	0.9 x V <sub>CC</sub>
• Max. output voltage	30 A
• Max. output current I <sub>max</sub>	10 A
• Continuous output current I <sub>cont</sub>	50 kHz
• Switching frequency of power stage	92 %
• Max. efficiency	1 kHz
• Band width current controller	25 000 rpm
• Max. speed (motor with 2 poles)	none
• Built-in motor choke per phase (min. necessary link inductances)	400 $\mu$ H

## Inputs

- Set value configurable -10 ... +10 V ( $R_i = 80 \text{ k}\Omega$ ), 0 ... +5 V ( $R_i = 50 \text{ k}\Omega$ )
- Enable +2.4 ... +50 VDC ( $R_i = 12 \text{ k}\Omega$ )
- Digital 1 (Switch «Monitor n» / «Monitor l») +2.4 ... +50 VDC ( $R_i = 17 \text{ k}\Omega$ )
- Digital 2 (Switch speed / current controller) +2.4 ... +50 VDC ( $R_i = 90 \text{ k}\Omega$ )
- STOP +2.4 ... +50 VDC ( $R_i = 17 \text{ k}\Omega$ )
- Encoder signals A, A\, B, B\, I, I\ max. 1 MHz 3-channels encoder is required
- Hall sensor signals H1, H2, H3

## Outputs

- Monitor can be configured with DIP switch 9: -10 ... +10 VDC ( $R_o = 1 \text{ k}\Omega$ ,  $f_g = 900 \text{ Hz}$ ) 0 ... 5 VDC ( $R_o = 1 \text{ k}\Omega$ ,  $f_g = 900 \text{ Hz}$ )
- Status reading «READY»; Open Collector max. 30 VDC ( $I_L < 20 \text{ mA}$ )

## Voltage outputs

- Encoder supply voltage +5 VDC, max. 100 mA
- Hall sensor supply voltage +5 VDC, max. 50 mA
- Auxiliary supply voltage +5 VDC, max. 20 mA

## Interface

- RS232 RxD; TxD (max. 115 200 Bit / s)  
high; low (max. 1 Mbit / s)
- CAN

## Trim potentiometers

- I<sub>max</sub>
- Offset
- I<sub>max</sub>
- gain

## LED indicator

- Bi-colour LED  
green = READY, red = ERROR

## Ambient temperature / humidity range

- Operation -10 ... +45°C
- Storage -40 ... +85°C
- No condensation 20 ... 80 %

## Mechanical data

- Weight approx. 400 g
- Mounting plate Flange for M4-screws

## Connection

- Power / Signal Power 6 pole / Signal 20 pole (2 x 10)  
Pitch Power 5.08 mm / Signal 2.54 mm  
Wire cross section: AWG 26 - 16  
Power 0.14 - 1.5 mm<sup>2</sup> multiple-stranded wire  
0.14 - 1.5 mm<sup>2</sup> single wire
- Encoder Signal 0.14 - 0.5 mm<sup>2</sup> multiple-stranded wire  
0.14 - 0.5 mm<sup>2</sup> single wire
- Encoder Plug DIN41651 (10 pole)  
for flat band cable, pitch 1.27 mm with AWG28

## Order number

- DES 70/10 digital 4-Q-EC Servoamplifier  
228597 in module housing

## Accessories

- 232359 Choke module 3 x 0.15 mH each 10 A  
223774 Encoder adapter according to DIN41651  
on screw terminal  
235811 Shunt regulator